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Amendments to the specification:

On page 1, after the title, please insert the following:

CROSS-REFERENCE

The invention described and claimed hereinbelow is also described in DE 103 15 407.8, filed April 4, 2003 and DE 10 2004 012434.5, filed March 13, 2004.
This German Patent Application, whose subject matter is incorporated here by reference, provides the basis for a claim of priority of invention under 35 U.S.C. 119 (a)-(d).

On page 1, line 2, please amend the heading as follows:

Prior Art Background of the Invention

On page 1, please amend the first paragraph as follows:

~~The invention is based on a quick-action chuck as generically defined by the preamble to claim 1.~~

On page 1, line 18, please amend the heading as follows:

Advantages Summary of the Invention

On page 4, line 17, please amend the heading as follows:

Brief Description of the Drawings Drawing

On page 5, line 19, please amend the heading as follows:

Detailed Description of the Exemplary Embodiment

Please amend the paragraph bridging pages 9-10 as follows:

If as described in conjunction with Fig. 3 the locking spring 22 has engaged the groove 28 in the base body 32, then the actuating element 20, for manually chucking the tool 34 with a clamping force appropriate for operation, is rotated onward counterclockwise, viewed in the direction of the free end. This situation is shown in Fig. 6, analogously to Fig. 4[:]. The locking spring 22 has snapped into the groove 28 of the base body 32, whereupon the locking devices 10 are fixed both axially and radially.

On page 16, please amend the abstract as follows:

Abstract of the Disclosure

~~The invention is based on a~~ A quick-action chuck, in particular for a power tool, ~~having~~ has an actuating element (20) and ~~having~~ a control device which includes at least one mechanism means (12, 22, 36, 42, 50) for controlling at least one locking device (10) that serves to absorb a chucking reinforcement force. ~~It is proposed that~~ via the locking device (10) that is controllable by the control device, a positive-engagement connection can be brought about for absorbing the chucking reinforcement force.

(Fig. 4)